

LECTURE: Q. ALGORITHMS FOR OPTIMIZATION

Base problem:

Binary quadratic optimization For A a symmetric, $n \times n$ matrix,

$$\textcircled{1} \quad \begin{aligned} &\text{maximize}_{x \in \mathbb{R}^n} \quad \langle x, Ax \rangle = \text{tr}(Axx^*) \\ &\text{s.t.} \quad x \in \{\pm 1\}^n \end{aligned}$$

Captures many important problems:

Maxcut (largest cut of a graph)

Community detection

(divide a network into sets of nodes belonging to two communities.)

Strategy

Phase I: Relax the problem $\left(\begin{array}{l} \text{NP-hard in worst-case so relax to} \\ \text{something easy in theory.} \end{array} \right)$

Phase II: optimization problem $\Rightarrow$ feasibility problem

Phase III: develop quantum-inspired meta-algorithm

quantum boost: use quantum subroutines.

MMW but without dual $\rightarrow$ mirror descent.

Based on arXiv 1909.04613

Phase I

S^n = set of $n \times n$ PSD matrices

SDP relaxation

② $xx^* \rightarrow X$

$$\max_{X \in S^n} \text{tr}(AX)$$

$$\text{s.t. } \text{diag}(X) = \vec{1}$$

$$X \succeq 0$$

~~$$\text{rank}(X) = 1$$~~

③ Rescaling

$$\max_{X \in S^n} \text{tr}(\tilde{A}X)$$

$$\tilde{A} = \frac{1}{\|A\|} A$$

$$\text{s.t. } \text{diag}(X) = \frac{1}{n} \vec{1}$$

$$\text{tr}(X) = 1 \rightarrow \text{superfluous constraint}$$

$$X \succeq 0$$

REMARK:

special case of a convex optimization problem

$$\max_{X \in \mathcal{C}_1 \cap \mathcal{C}_2} f(X) = \text{tr}(\tilde{A}X)$$

$$X \in \mathcal{C}_1 \cap \mathcal{C}_2 \text{ where}$$

$$\mathcal{C}_1 = \{X : \text{diag}(X) = \frac{1}{n} \vec{1}\} \text{ affine subspace}$$

$$\mathcal{C}_2 = \{X : X \succeq 0\} \text{ convex cone}$$

But algorithm will work for general cvx problems:

$$\max f(X), f \text{ bdd, concave}$$

$$\text{s.t. } X \in \mathcal{C}_1 \cap \dots \cap \mathcal{C}_m \text{ where } \mathcal{C}_1, \dots, \mathcal{C}_m \text{ are convex sets.}$$

$$\text{tr}(X) = 1, X \succeq 0.$$

Phase II

suffices to solve the following feasibility problem:

notice diff!

$$\boxed{\begin{array}{l} \text{Find } X \in S_n \text{ s.t.} \\ \text{tr}(\tilde{A}X) \leq \lambda \\ \text{diag}(X) = \frac{1}{n} \mathbf{1} \\ \text{tr}(X) = 1 \\ X \succeq 0 \end{array}}$$

Assume $\tilde{A}$
has bounded
norm.
 $\rightarrow \text{tr}(\tilde{A}X) \in \text{interval}$

By wrapping this in an outer loop where we binary search the interval to choose val of λ only need

$$(\log(1/\epsilon))$$

queries to get multiplicative

ϵ -approximation

Phase III

quantum-inspired change of variables

$$X = \rho_H = \frac{\exp(-H)}{\text{tr}(\exp(-H))} \in S_n \quad (\text{Gibbs state})$$

- ensures X is PSD, trace 1.

New problem:

$$\boxed{\begin{array}{l} \text{let } \tilde{A} = \frac{A}{\|A\|}, \\ \text{find } H \in S^n \text{ s.t.} \quad \text{tr}(\tilde{A}\rho_H) \leq \lambda \quad (\rho_H \in \mathcal{A}_n) \\ \text{diag}(\rho_H) = \frac{\mathbf{1}}{n} \quad (\rho_H \in \mathcal{D}_n) \end{array}}$$

Again: can solve this for any # convex constraints.

The algorithm

WILL ASSUME ACCESS TO ORACLE:

Def (ϵ -separation oracle)

contains every line segment btw 2 points in the set

Let $C \subset S_n$ be a closed, convex subset of q -states

$C^* \subset \{X = X^T \in \mathbb{C}^{n \times n} : \|X\| \leq 1\}$ closed, convex subset of observables.
"tests"

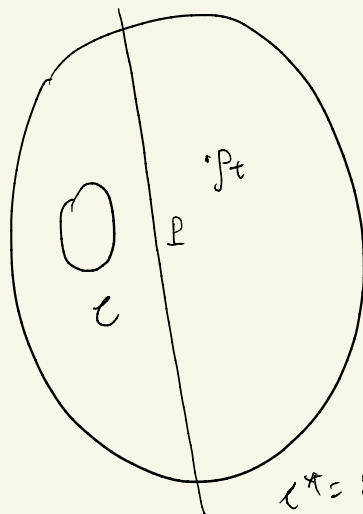
$$O_{C, \epsilon}(p) = \begin{cases} \text{accept } p & \text{if } \min_{Y \in C} \max_{L \in C^*} \text{tr}(L(p - Y)) \leq \epsilon \end{cases}$$

Interpretation: observables from C^* cannot distinguish p from elements of C

else: output $L \in C^*$ s.t. $\text{tr}(L(p - Y)) \geq \frac{\epsilon}{2} \quad \forall Y \in C$.

Interpretation: there is an observable to which p looks different from all states in C

Intuition:



$C^* = \text{set of planes.}$

ANIMATION:

If an oracle told me L , I could always improve my guess to push towards C .

Algorithm "Hamiltonian updates" for convex feasibility problems.

start w/ $H=0$ ("infinite temperature"), $p_H = \mathbb{I}/n$

for $t = 1, \dots, T$,

- check if $p_H \in A_\lambda$ and $p_H \in D_n$ by querying $O_{A_\lambda, \epsilon}$, $O_{D_n, \epsilon}$

if true we are done

else update H to penalize infeasible directions.

↳ given separating hyperplane P , update

$$H \leftarrow H + \frac{\epsilon}{16} P$$

- $p_H \leftarrow \exp(-H) / \text{tr}(\exp(-H))$

Convergence proof

Theorem (Brandão, Kueng, Francia).

Hamiltonian updates finds an approximately feasible point after

(at most) $T = \lceil 16 \log(n)/\epsilon^2 \rceil + 1 = \tilde{O}(1)$ steps.

Otherwise, the problem is infeasible.

Proof idea:

starting state

- relative entropy between $p = \frac{\mathbb{I}}{n}$ and any feasible point p^* is bdd:

$$S(p^* \| p_0) \leq \log(n).$$

- show that each iteration makes constant progress in relative entropy: (let p^* = feasible point)

$$S(p^* \| p_{t+1}) - S(p^* \| p_t) \leq -\frac{\epsilon^2}{16}$$

$\Rightarrow$ convergence after at most T steps, or $S(p^* \| p_T) < 0$. impossible by defn of rel. ent.

Remark:

= mirror descent with VN entropy potential function.

↳ Bregman divergence wrt VN entropy

$$= \text{KL divergence} \quad \hookrightarrow D_h(y||x) := h(y) - h(x)$$

$$- \langle \nabla h(x), y-x \rangle$$

for h any strictly convex function.

Proof of (1)

$$\text{Suppose } \exists \text{ feasible point } p^*, \text{ let } p_t = \frac{\exp(-H_t)}{\text{Tr}(\exp(-H_t))}$$

Distance @ time = 0

$$S(p^*||p_0) = \text{Tr}(p^*(\log p^* - \log p_0)) \leq \log(n)$$

improvement at every step:

$$S(p^*||p_{t+1}) - S(p^*||p_t) = \text{tr}(p^*(\log p_t - \log p_{t+1}))$$

$$= \text{tr}(p^*(-H_t - \log \text{Tr}(\exp(-H_t)) + H_{t+1} + \log \text{Tr}(\exp(-H_{t+1}))))$$

$$= \text{tr}(p^*(H_{t+1} - H_t)) + \log \left(\frac{\text{Tr}(\exp(-H_{t+1}))}{\text{Tr}(\exp(-H_t))} \right)$$

Recall update step:

$$H_{t+1} = H_t + \frac{\epsilon}{16} p_t$$

$$= \frac{\epsilon}{16} \text{tr}(p^* p_t) - \log \left(\frac{\text{Tr}(\exp(-H_{t+1} + \frac{\epsilon}{16} p_t))}{\text{Tr}(\exp(-H_{t+1}))} \right)$$

bad boi

(*)

(a book mark!)

Useful facts to analyze bad boi

(i) Peierls - Bogoliubov inequality: $\log(\text{tr}(\exp(F+G))) \geq \text{tr}(F \exp(G))$

(ii) $\text{Tr}(e^{-H/c}) = \text{Tr}(e^{-H} \cdot e^{-\log c} I)$ provided $\text{tr}(\exp(G)) = 1$

$\uparrow$
scalar

$$= \text{Tr}(\exp(-H - (\log c) I))$$

"putting scalars in the exponent".

by (i), bad boi becomes

$$= \log \left(\text{Tr}(\exp(\overbrace{-H_{t+1}}^G - \log(\text{Tr}(\exp(-H_{t+1}))) I + \overbrace{\frac{F}{16}}^F P_t) \right)$$

by (i)

$$\geq \text{Tr} \left(\frac{\epsilon}{16} P_t \exp(-H_{t+1} - \log(\text{Tr}(\exp(-H_{t+1}))) I \right)$$

$$= \frac{\epsilon}{16} \text{Tr} \left(P_t \frac{\exp(-H_{t+1})}{\text{Tr}(\exp(-H_{t+1}))} \right) = \frac{\epsilon}{16} \text{tr}(P_t \rho_{t+1})$$

end {badboi analysis}

Continuing from (*), $S(\rho^* \| \rho_{t+1}) - S(\rho^* \| \rho_t) = \frac{\epsilon}{16} \text{tr}(P_t (\rho^* - \rho_{t+1}))$

Fact. Let H, H' be Hermitian matrices. Then

$$\left\| \frac{e^H}{\text{Tr}(e^H)} - \frac{e^{H'}}{\text{Tr}(e^{H'})} \right\|_1 \leq 2(e^{\|H-H'\|} - 1)$$

$$\leq \frac{\epsilon}{16} \left(\text{tr}(P_t (\rho_t - \rho_{t+1})) - \text{tr}(P_t (\rho_t - \rho^*)) \right)$$

$$\leq \frac{\epsilon}{16} \left(\|P_t\| \|\rho_t - \rho_{t+1}\|_{\text{tr}} - \frac{\epsilon}{2} \right) \quad \text{by defn of } \epsilon\text{-separation oracle.}$$

$$\leq 2 \left(\exp\left(\frac{\epsilon}{16} \|P_t\|\right) - 1 \right)$$

$$\leq \frac{\epsilon}{4} \quad \because \|P_t\| \leq 1.$$

(see arXiv 1609.05537 for proof)

$$\leq \frac{\epsilon}{16} \left(\frac{\epsilon}{4} - \frac{\epsilon}{2} \right) = -\frac{\epsilon^2}{64}.$$

Runtime of algorithm

Computational cost

Total # iterations of Hamiltonian updates:

$$T = \lceil 16(\log(n)/\epsilon^2) \rceil + 1 = \tilde{O}(1)$$

Per-iteration runtime:

CLASSICAL: $\rightarrow$ rate-limiting step!

Each step requires:

matrix exponentiation

- (i) compute Gibbs state: $O(n^3)$ ($n = \text{matrix dimension}$)
- (ii) compute trace (check if $p \in A_2$): $O(ns)$ ($s = \text{row sparsity}$)
- (iii) check diagonal $\sim \mathbb{I}/n$ ($p \in \mathcal{D}_n$): $O(n)$.

SIDENOTE: they obtain a better classical algorithm for quadratic SDP relaxations too, by approximating step i).

$$\rightarrow \tilde{O}(n^{2.5}) \text{ runtime prev: } \tilde{O}(n^{2.5}s)$$

Key idea: truncate Taylor expansion of $\exp(-H)$.

$$\exp(-H) \simeq \sum_{k=0}^L \frac{H^k}{k!}, \quad L = O(\log(n)/\epsilon) = \tilde{O}(1)$$

+ proof of convergence is robust to approximation of β_H .

Result: Quantum SDP solver via Gibbs sampling

Classical bottleneck: compute Gibbs states

Quantum speedup:

prepare copies of ρ_H on q. computer. $\tilde{O}(\sqrt{n} \log n)$

Estimate $\text{tr}(\tilde{A} \rho_H)$ via phase estimation $O(1/\epsilon^2)$ copies

Estimate $\text{diag}(\rho_H)$ via computational basis meas. $O(n/\epsilon^2)$ copies.

distribution learning lower bound.

Theorem:

Hamiltonian updates app. solves binary quadratic SDP relaxations in q. runtime $\tilde{O}(n^{1.5} (\sqrt{n})^{1+o(1)})$

Details about q. subroutine:

Hamiltonians are very structured:

$$H = \alpha \tilde{A} + \beta D, \quad \alpha, \beta = O(\log(n)/\epsilon)$$

① [Paulin, Wocjan] preparing ρ_H reduces to simulating time evolution

② [Childs, Wiebe, 2012]: split up time evolution

③ [Low 2019]: implementing $\exp(it\alpha\tilde{A})$ costs $\tilde{O}(\sqrt{n}^{1+o(1)})$

④ [Prakash; 2014] implementing $\exp(it\beta D)$ w/ qRAM costs

$$\tilde{O}(n)$$

$\Rightarrow$ total cost: $\tilde{O}(n^{1.5} \sqrt{n}^{1+o(1)})$

Limitations of optimization algo (Bonus application of rel. ent convergence, from 2009.05532)

Fix Hamiltonian H .

Let $\tilde{\rho}$ be "close" to min. state $\mathbb{I}/2^n$.

$$D(\tilde{\rho} \| \mathbb{I}/2^n) \leq \beta \epsilon \|H\|.$$

Then

$$\text{Tr}(H\tilde{\rho}) \geq \text{Tr}(G_\beta H) - \epsilon \|H\|.$$

$$G_\beta := \frac{e^{-\beta H}}{\text{Tr}(e^{-\beta H})}$$

$$\Leftrightarrow |\text{Tr}(H(\tilde{\rho} - G_\beta))| \leq \epsilon \|H\|.$$

pf

$$f(\beta) = \log(\overbrace{\text{Tr}(e^{-\beta H})}^{Z_\beta}) \text{ is differentiable}$$

$$\rightarrow \text{MVT: } \exists \tilde{\beta} \in (0, \beta) \text{ s.t. } \frac{f(0) - f(\beta)}{\beta} = -f'(\tilde{\beta}) = \text{Tr}(G_{\tilde{\beta}} H)$$

$$\underbrace{\text{Tr}(G_{\tilde{\beta}} H)}_{\langle E \rangle_{\tilde{\beta}}} \geq \underbrace{\text{Tr}(G_\beta H)}_{\langle E \rangle_\beta}$$

b/c $\tilde{\beta}$ at higher temperature than β .

Fact: Variational formulation of rel. ent. for any ϕ

$$Z_{\beta, \phi} := \text{Tr}(e^{-\beta H + \log(\phi)})$$

$$\Rightarrow \text{Tr}(\underbrace{\tilde{\rho}}_{\tilde{\rho}} H) \geq \sup_{\beta \geq 0} \underbrace{\beta^{-1} (\log(Z_{\beta, \phi}) - D(\tilde{\rho} \| \phi))}_{\substack{\downarrow \text{For } \phi := \frac{\mathbb{I}}{2^n} \\ n - \log(Z_\beta)}} \underbrace{\frac{\mathbb{I}}{2^n}}_{\frac{\mathbb{I}}{2^n}}$$

Let:

$$\rightarrow \text{Tr}(H\tilde{\rho}) \geq \underset{\uparrow}{\text{Tr}(G_{\tilde{\rho}} H)} - \beta^{-1} D(\tilde{\rho} \| \mathbb{I}/2^n) \geq \text{Tr}(G_{\tilde{\rho}} H) - \epsilon \|H\|.$$

From Fact